



# Artificial intelligence for mobility assistance robots

Record number : OPR-773

## Overview

### RESEARCH DIRECTION

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### INFORMATION

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### ADMINISTRATIVE UNIT(S)

Faculté de génie  
Département de génie électrique et de génie informatique  
Département de génie mécanique  
Institut interdisciplinaire d'innovation technologique (3IT)

### LEVEL(S)

2e cycle  
3e cycle  
Stage postdoctoral

### LOCATION(S)

3IT - Institut interdisciplinaire d'innovation technologique

## Project Description

Arjo and Université de Sherbrooke are partnering to develop collaborative-robotic technologies for the next generation of transfer devices used in hospitals and long-term care units. The goal of this Alliance project is to develop lifting robot assistants and an eco-system of devices for a smart hospital room concept that would release caregivers of time-consuming, low-value tasks and empower patient with mobility assistance features. The proposed assistance technology aims to address these two societal problems: 1) improving the caregivers' health and work-conditions with assistance scheme limiting the physical efforts during patient transfers and 2) improving the patients' care quality by facilitating occasions for them to move out of their bed.

The first step in the project, which will be entrusted to a graduate student supported by an engineering team at 3IT, is to develop various algorithms to make the robot assistants smart and proactive. First a perception system to locate users in the room will be developed. Then several axes of intelligence will be explored, for example 1) a smart button-free human machine interface where the system automatically interpret the user intents and act accordingly, 2) adaptive rehabilitation programs and 3) progress monitoring tools to assist therapists in their assessment of patients.

Keywords: motion planning, sensors, autonomous systems, AI

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## Discipline(s) by sector

Sciences naturelles et génie

Génie électrique et génie électronique,  
Génie mécanique

## Funding offered

Yes

The last update was on 12 March 2024. The University reserves the right to modify its projects without notice.